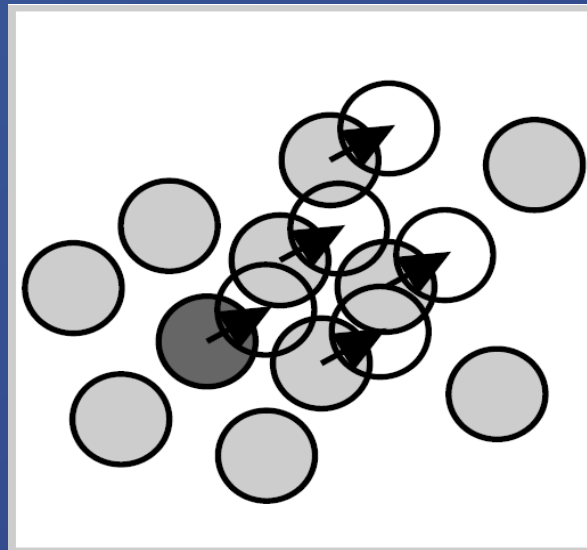


Cluster-Algorithms for off-lattice systems



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FR PHYSIK



Cluster-Algorithms for off-lattice systems

- The Monte Carlo-Method: A reminder
- Cluster Algorithms
- Cluster-Algorithm of Dress & Krauth
- The Avalanche-Algorithm

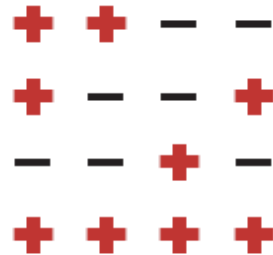


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The Monte Carlo-Method

Ising-model:



Hamiltonian:

$$H = - \sum_{\langle ij \rangle} s_i s_j$$

Magnetisation

$$\langle M_i \rangle = \frac{1}{Z} \sum_{\{S\}} s_i \exp(-\beta H(S))$$

Partition-function:

$$Z = \sum_{\{S\}} \exp(-\beta H(S))$$

Exact enumeration:

System-Size

6x6

7x7

8x8

...

CPU-Time

1 minute

6 weeks

7600 years

→ Exact enumeration only possible for small system sizes!



The Monte Carlo-Method

Naive method

- Random generation of configurations
- Estimate of expectation values from a finite number of configuration
- Example: Magnetisation

$$\langle m_i \rangle = p^{(1)} s_i^{(1)} + p^{(2)} s_i^{(2)} + p^{(3)} s_i^{(3)} + \dots$$

$s_i^{(j)}$ magnetisation at site i in configuration j

Relative weight: $p^{(i)} = \exp(-\beta H(S^{(i)}))$

Problem of the method:

- A relative small fraction of the configurations determines the averages
- By unbiased sampling we always hit configurations with small weight

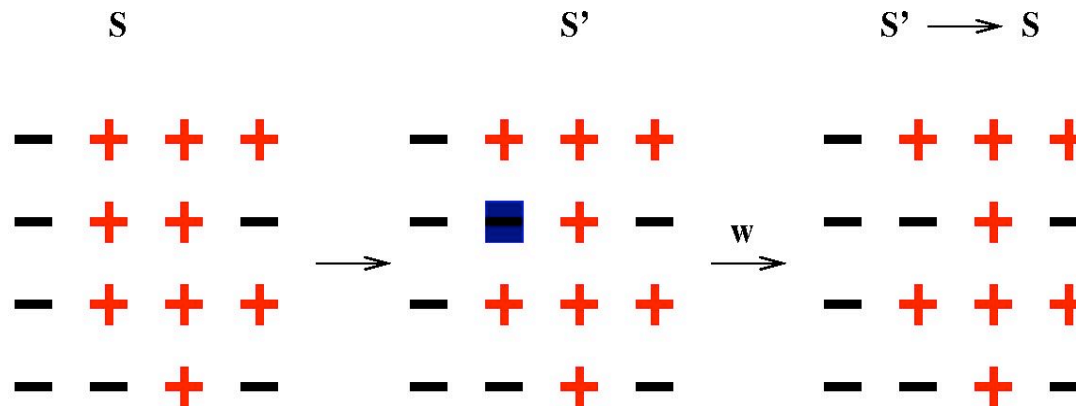
→ Biased sampling in order to hit the important ones

The Monte Carlo-Method: Importance Sampling

Idea: Generate configurationen with probability corresponding to their weight!

Realisation:

1. Generate a random configuration S
2. Select a site i and perform a spinflip
3. **If** spinflip lowers the energy *always* accept the move
else accept with probability $w(S \rightarrow S')$



Monte Carlo-Method: Detailed Balance

Complete algorithm: How to choose $w(S \rightarrow S')$?

Configuration have to be generated according to their relative weight!

→ Stationary probabilities of the stochastic process have Boltzmann-Weight

Master-equation:
$$\frac{\partial P(S, t)}{\partial t} = \sum_{S'} (w(S' \rightarrow S)P(S', t) - w(S \rightarrow S')P(S, t))$$

Stationary solution
$$0 = \sum_{S'} (w(S' \rightarrow S)P(S') - w(S \rightarrow S')P(S))$$

Detailed balance:
$$\frac{w(S \rightarrow S')}{w(S' \rightarrow S)} = \frac{P(S')}{P(S)} = \exp(-\beta (H(S') - H(S)))$$

Metropolis
$$w(S \rightarrow S') = \begin{cases} \exp(-\beta (H(S') - H(S))) & H(S') > H(S) \\ 1 & H(S') \leq H(S) \end{cases}$$

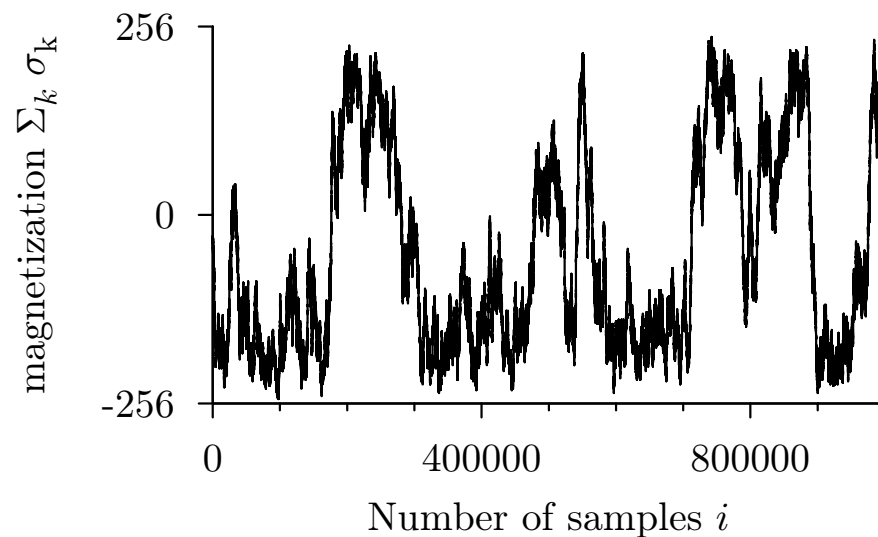




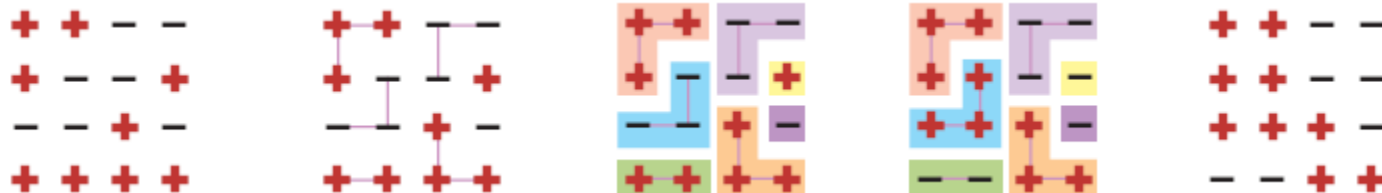
Problem of the algorithm:

Configurations depend on the history

→ Configuration space is only partially explored



Improved Algorithms: Simultaneous update of many sites



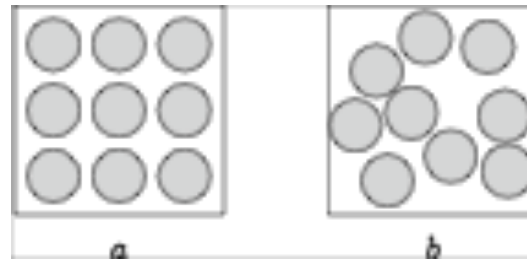
Swendsen-Wang-Cluster-Algorithm:

1. Set a bond with prob. $w_{ij} = 1 - \exp(-2\beta)$ neighboring spins (i,j)
2. Identification of clusters
3. Flip clusters with prob. $\frac{1}{2}$
4. Delete bonds

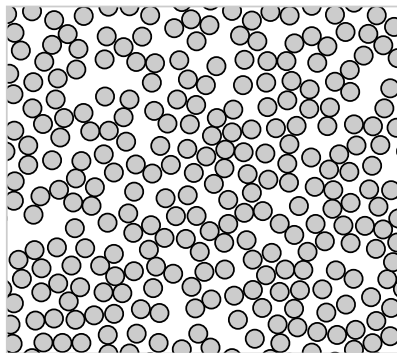
→ Decorrelation of the configurationen + Importance Sampling

Hard disks as a model for 2d crystal

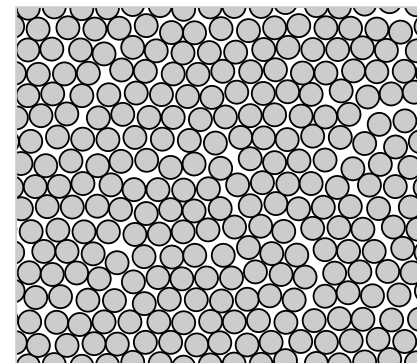
Configurations without overlap have **equal weight**



Phase transition: Liquid/crystal (bond orientational order)



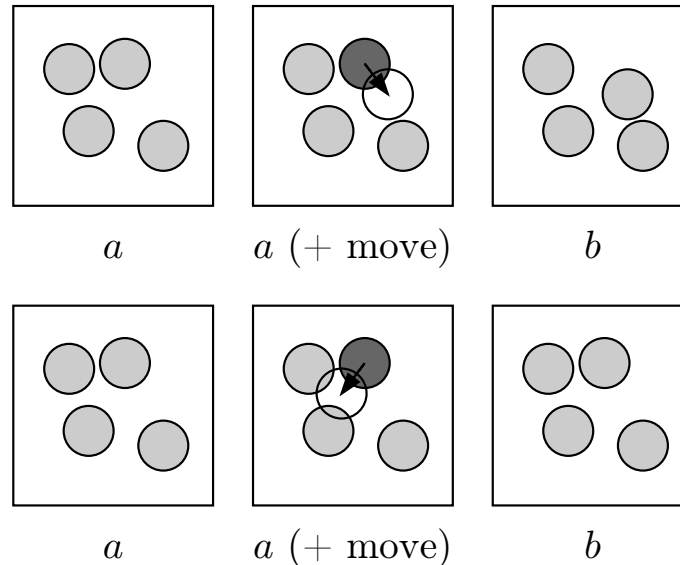
$\eta = 0.48$



$\eta = 0.72$

Off-Lattice Models

Local algorithm:



1. Select a particle and a displacement vector
2. Overlap? Reject; else: accept

Detailed balance

- All configurations without overlap have equal probability
- Inversion of the update: Inverse displacement vector, same particle

→ Accept all moves leading to valid configurations

Off-Lattice Models

Local algorithm:

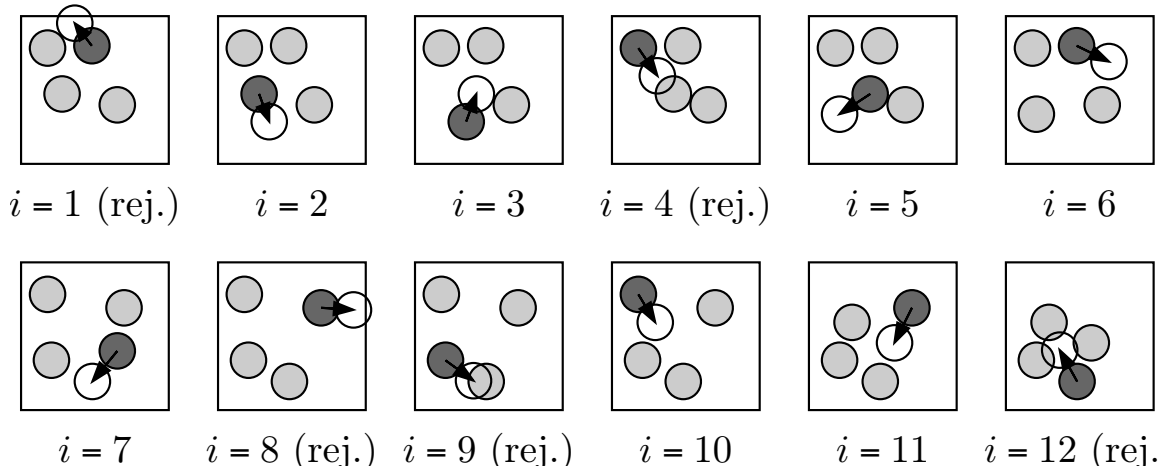
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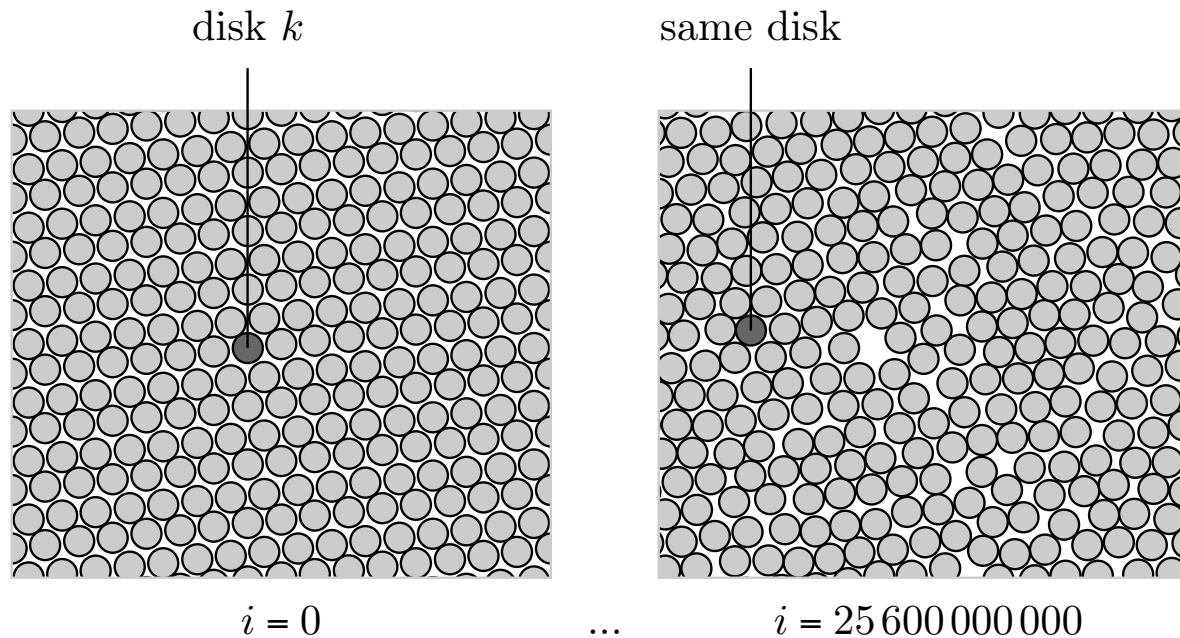
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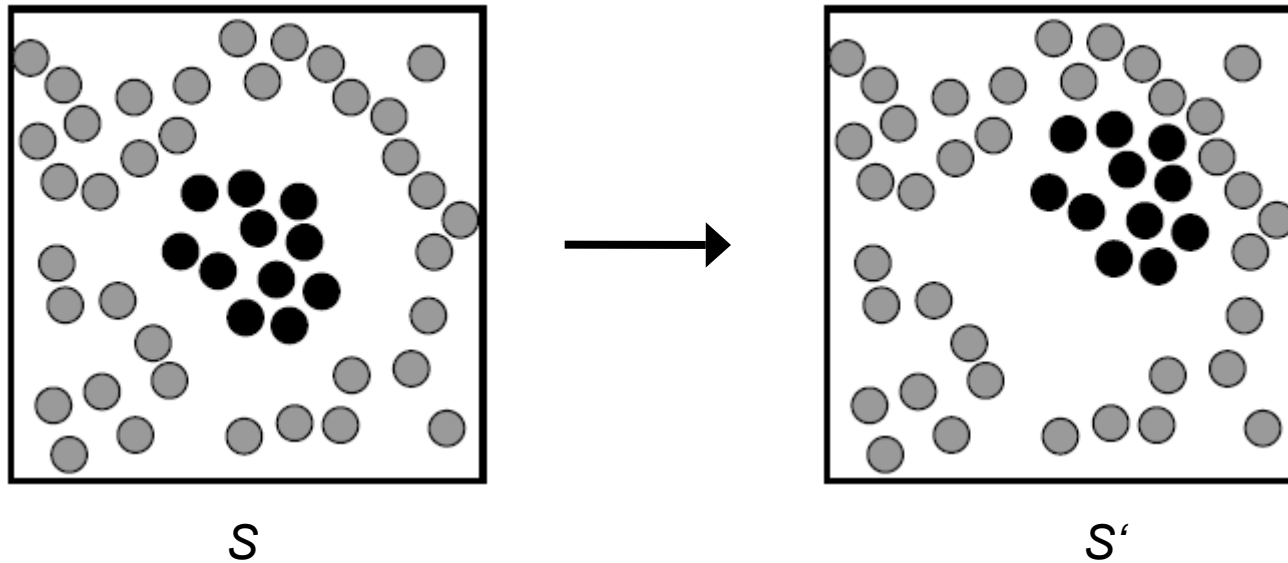
→ Accept all moves leading to valid configurations

Problems of the local algorithm:



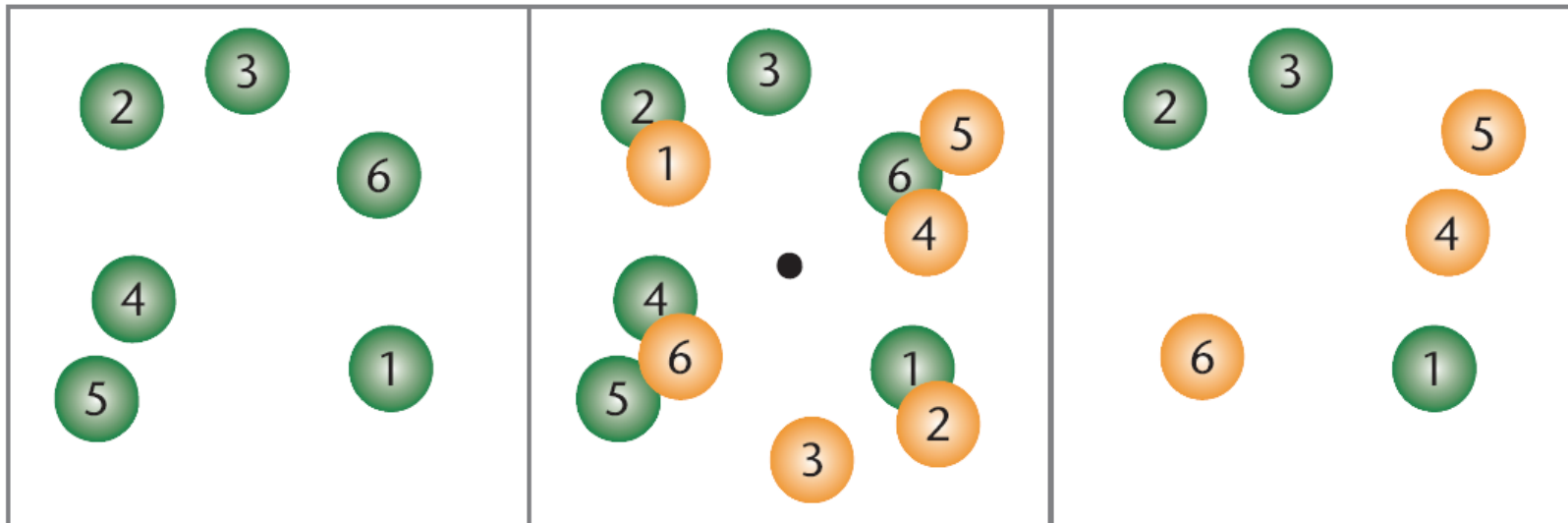
→ Local algorithm is frozen at high densities!

What is a Cluster?



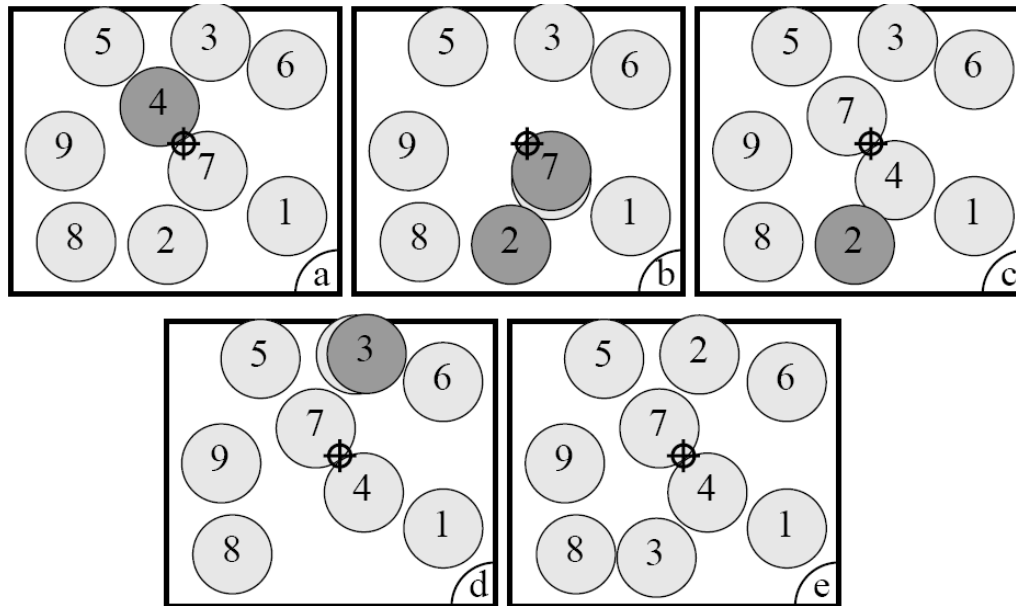
Probability to select cluster in S much larger than in S'
→ Low acceptance-rate

Looking for update with equal probability for cluster selection:



Idea: Exchange Clusters between configuration (S , green) and mirror image (S' , orange)

Realisation:

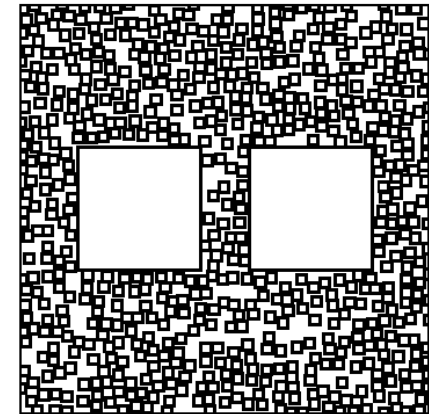
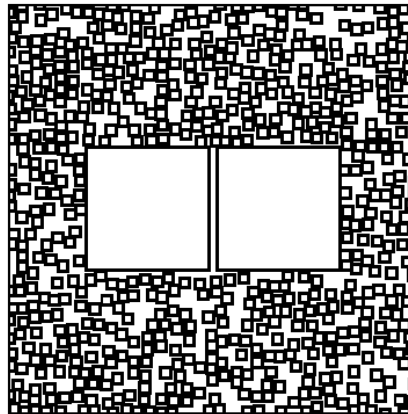


- Select an arbitrary pivot
- Reflect the particle position
- Iterate the procedure until a valid configuration is generated

Applications of the cluster algorithm

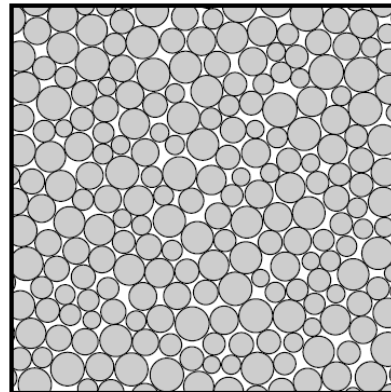
Binary mixtures:

„Depletion Forces“

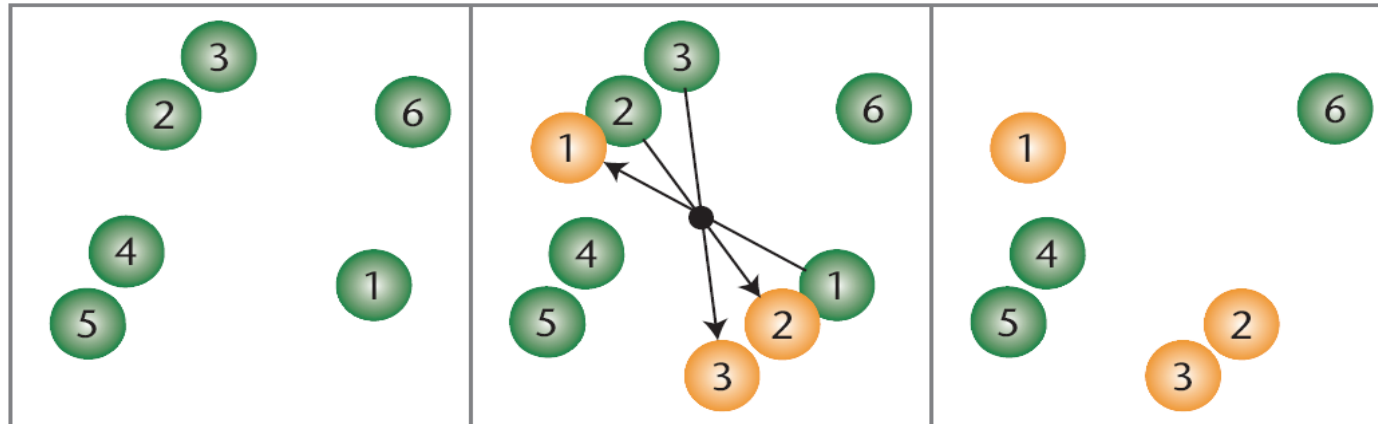


Polydisperse systems:

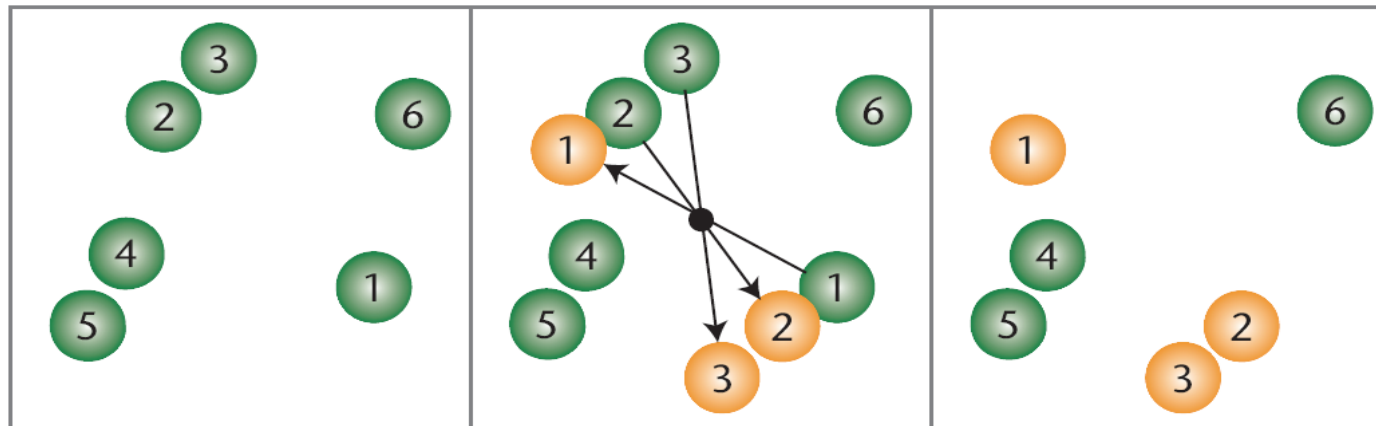
Equilibration beyond the dynamical transition



Extension: Rejection-free algorithm for interacting systems (Liu & Luijten)

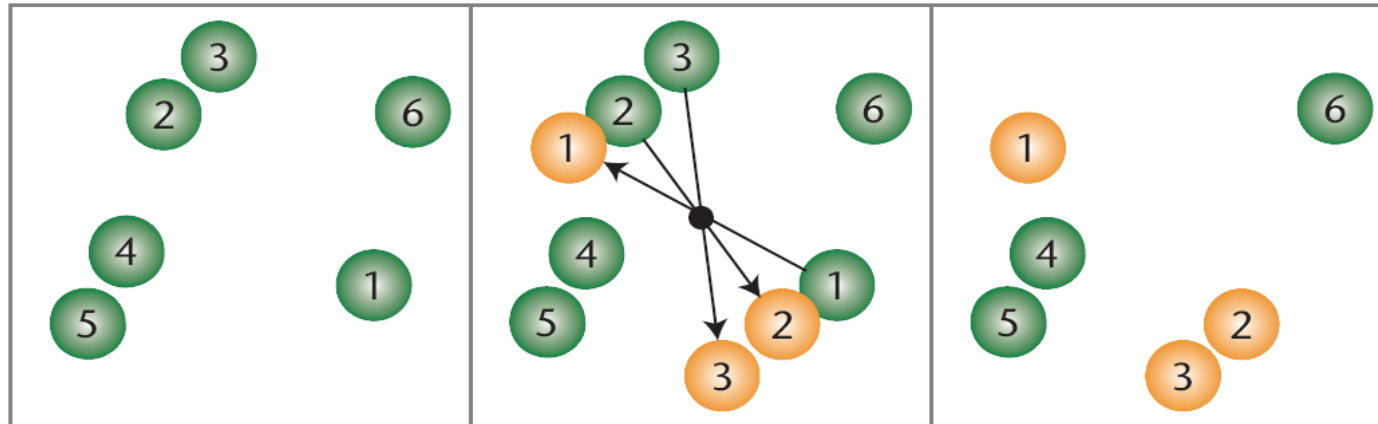


Extension: Rejection-free algorithm for interacting systems (Liu & Luijten)

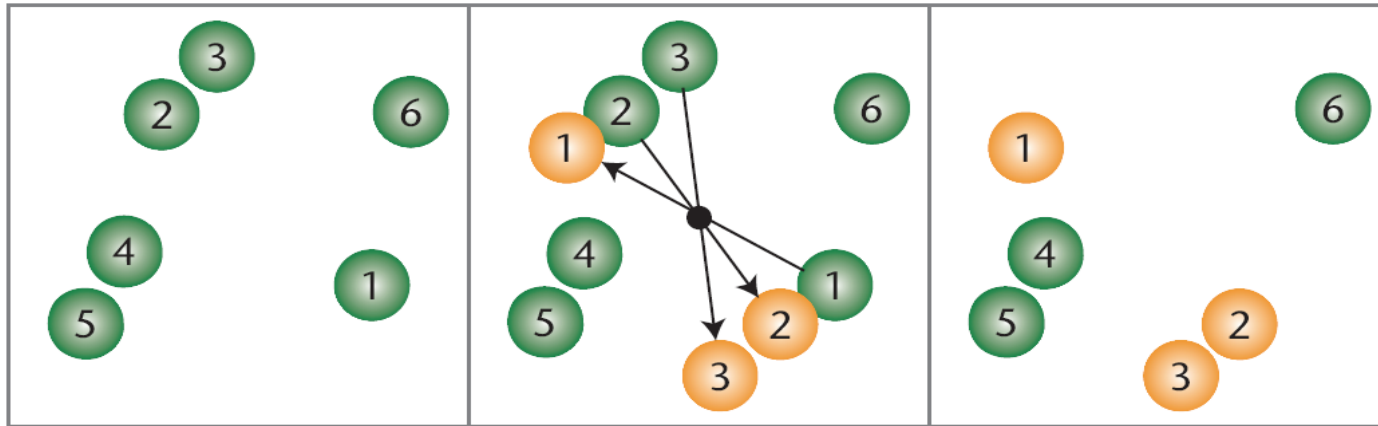


- Start cluster-construction: Select a particle and a pivot
- Add a new particle with prob. $p_{ij} = \max[1 - \exp(-\beta\Delta_{ij}), 0]$.
- Add new particles to a list
- Flip particles until the list is empty

Extension: Rejection-free algorithm for interacting systems (Liu & Luijten)



Extension: Rejection-free algorithm for interacting systems (Liu & Luijten)



Problem: The algorithm is not efficient at high densities!

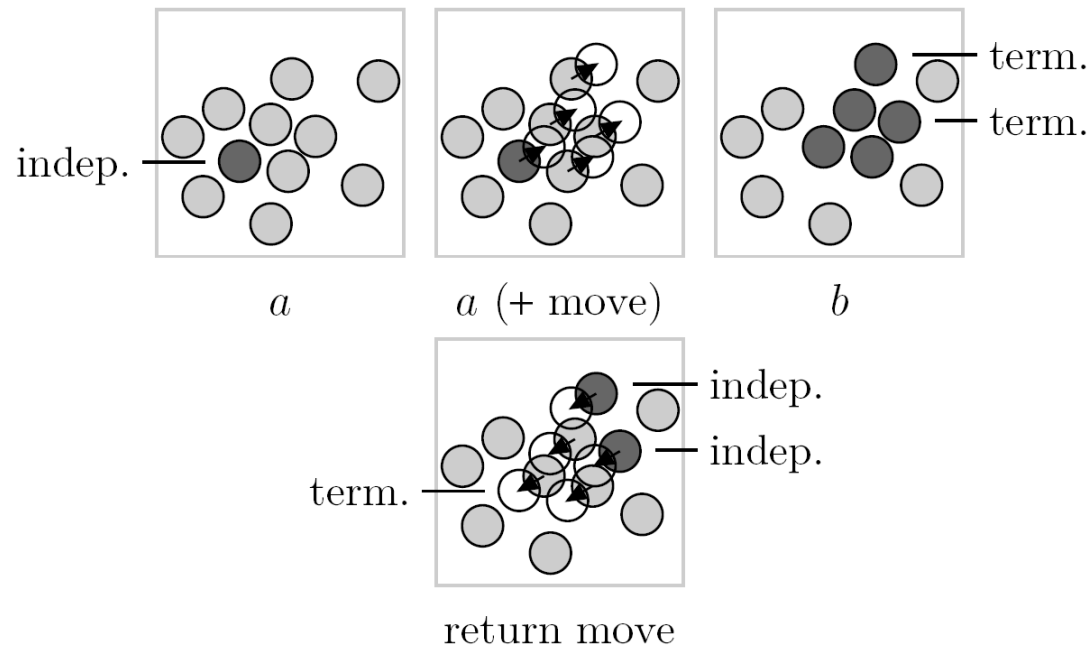
Avalanche algorithm



Idea: Generate cluster-moves by iteration of the elementary shift of the particles (avalanches)

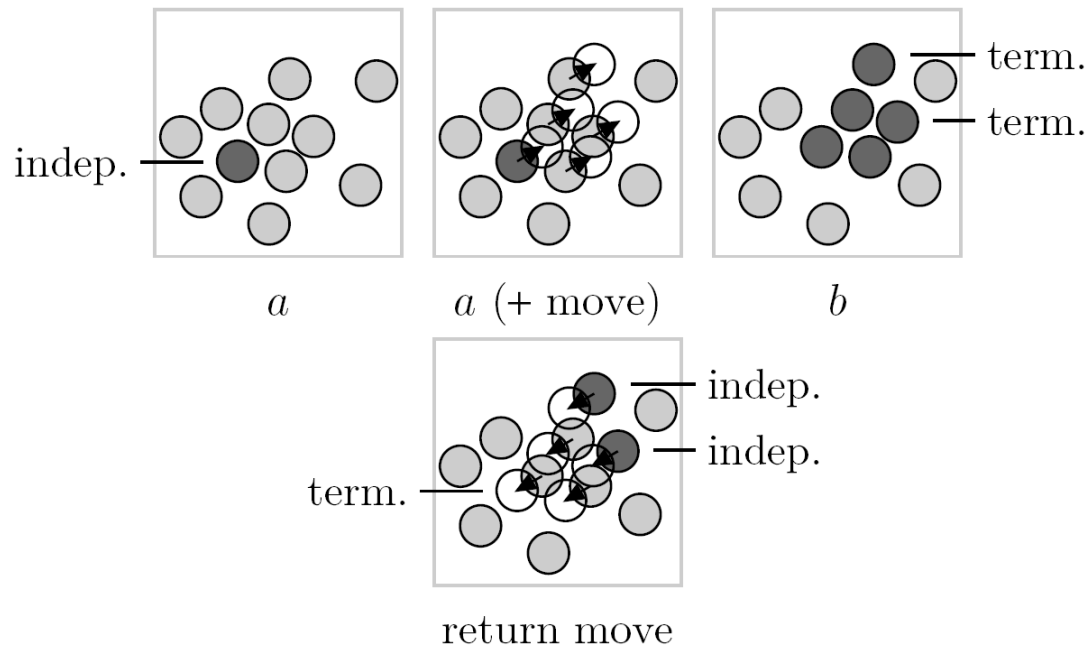
Avalanche algorithm

Idea: Generate cluster-moves by iteration of the elementary shift of the particles (avalanches)



Avalanche algorithm

Idea: Generate cluster-moves by iteration of the elementary shift of the particles (avalanches)



Naive algorithm:

- Random choice of a disk i and a displacement vector δ
- Iterate until a valid configuration is obtained
- Return-move?

Avalanche algorithm



Detailed Balance:

$$\Pi(a) \underbrace{A(a \rightarrow b)}_{\textit{selection}} \underbrace{P(a \rightarrow b)}_{\textit{acceptance}} = \Pi(b) \underbrace{A(b \rightarrow a)}_{\textit{selection}} \underbrace{P(b \rightarrow a)}_{\textit{acceptance}}$$

Avalanche algorithm



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All (allowed) configurations have the same weight

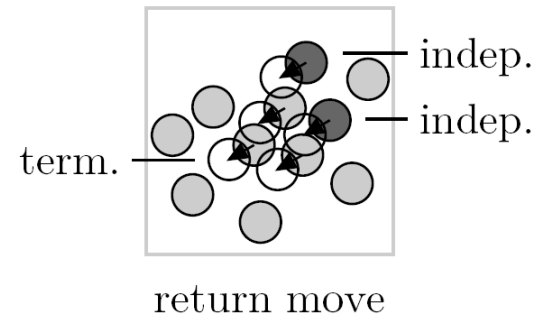
Avalanche algorithm



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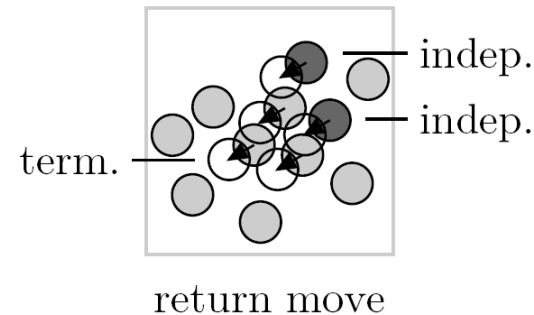
Return-move $b \rightarrow a$ two particles needed to push the cluster (independent set)
→ Rejection of the Update

Avalanche algorithm

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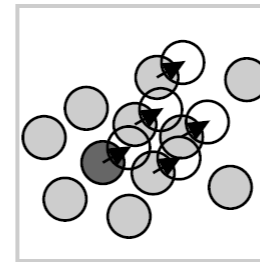
Solution (basic idea):

Generalisation of the cluster-construktion

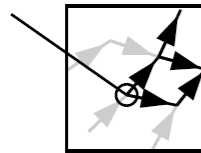
The avalanche-algorithm



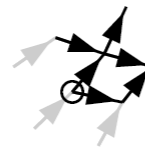
Move: $a \rightarrow b$



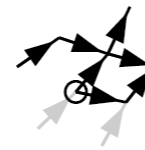
disk l



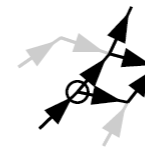
$k = 1$



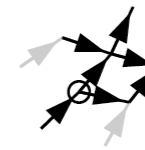
$k = 2$



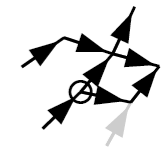
$k = 3$



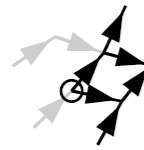
$k = 4$



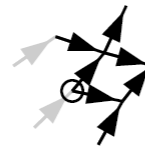
$k = 5$



$k = 6$



$k = 7$



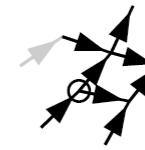
$k = 8$



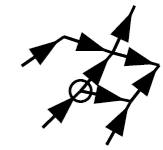
$k = 9$



$k = 10$



$k = 11$



$k = 12$

Prob. to select the cluster: $A(a \rightarrow b) = 1/12$

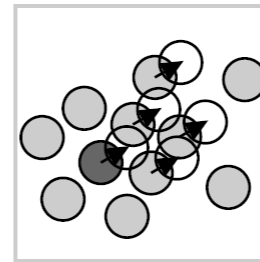
The avalanche-algorithm



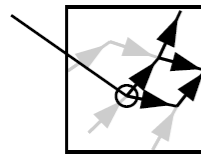
Recipe:

Construction of a graph, i.e. particles that overlap if shifted by $\pm\delta$ and include disk l

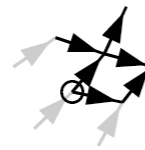
Move: $a \rightarrow b$



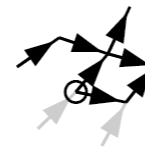
disk l



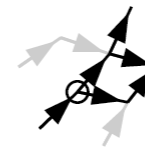
$k = 1$



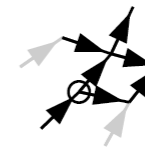
$k = 2$



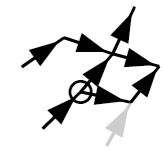
$k = 3$



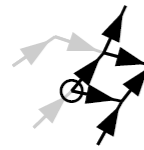
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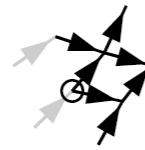
$k = 5$



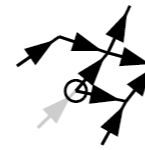
$k = 6$



$k = 7$



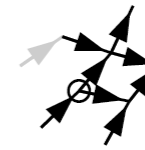
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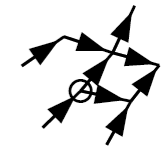
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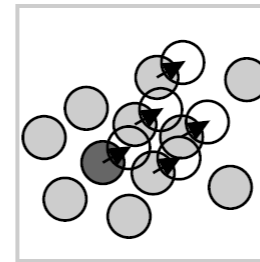
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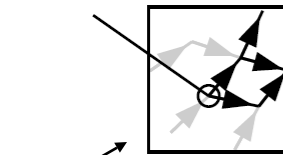
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Move: $a \rightarrow b$



disk l



Generation of 12
Clusters is possible

$k = 1$

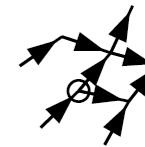
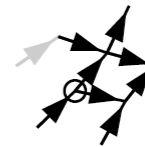
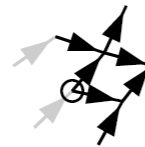
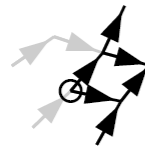
$k = 2$

$k = 3$

$k = 4$

$k = 5$

$k = 6$



$k = 7$

$k = 8$

$k = 9$

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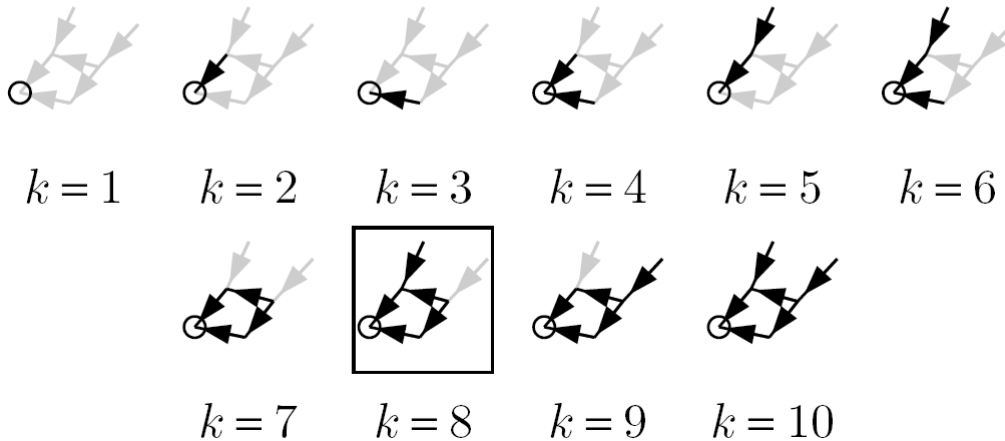
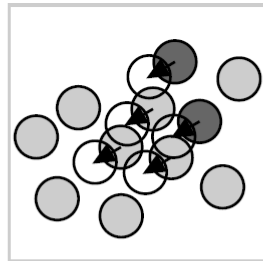
Prob. to select the cluster: $A(a \rightarrow b) = 1/12$

The avalanche-algorithm



Return-Move

$b \rightarrow a$



Detailed balance:

$$P(a \rightarrow b) = \min\left(1, \frac{A(b \rightarrow a)}{A(a \rightarrow b)}\right)$$

Here: $P(a \rightarrow b) = 1$

Selection-Prob.: $A(b \rightarrow a) = \frac{1}{10}$

Avalanche algorithm

Elements of the algorithm:

- (1) Construction of the graph
- (2) Choice of the cluster

Avalanche algorithm

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- (1) Construction of the graph
- (2) Choice of the cluster

Principle advantages:

It is possible to select the amplitude

→ *Tuning of the cluster-size!*

→ *Efficient at large densities !?*

Avalanche algorithm

Elements of the algorithm:

- (1) Construction of the graph
- (2) Choice of the cluster

Principle advantages:

It is possible to select the amplitude

→ *Tuning of the cluster-size!*

→ *Efficient at large densities !?*

Problem the Algorithm:

*Counting clusters is a **NP-complete problem!***

Naive Algorithm: 2^N possibilities (N=# independent particles- im Graph)

Avalanche algorithm

More efficient implementation:

- i. Choose the displacement vector δ
- ii. Select a particle with prob. p as a pivot particle
- iii. Accept the cluster-move with prob. $P_{acc}(i \rightarrow f)$

A priori probability:

$$A(i \rightarrow f) = p^{N_{ind}} (1 - p)^{N_{\bar{c}}}$$

Acceptance probability:

$$P_{acc}(i \rightarrow f) = p^{N_{ind}^f - N_{ind}^i} = p^{\Delta}$$

Generalisation to individual probabilities is possible!

Problem the Algorithm:

High acceptance rate only if Δ is small!

Summary

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- **Rejection-free cluster** algorithms slow at high densities

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- **Avalanche algorithm:** Tuning of the cluster-size possible; high rejection rates for large clusters
- Performance not comparable to lattice models
- For several systems perform cluster algorithms better than the standard algorithm

Summary

- **Rejection-free cluster** algorithms slow at high densities
- **Avalanche algorithm:** Tuning of the cluster-size possible; high rejection rates for large clusters
- Performance not comparable to lattice models
- For several systems perform cluster algorithms better than the standard algorithm
- Open question: How to choose the selection probabilities for the avalanche algorithm?

Thanks to

- Werner Krauth, LPS, ENS, Paris
- Markus Bellion, now at BaFin
- Heiko Rieger, Saarland University
- DFG for funding

Further reading:

W.Krauth, *Statistical Mechanics: Algorithms and Computations*, Oxford Univ. Press. (2006)

A. Buhot & W. Krauth, *Phys.Rev. E* 59, 2939 (1999)

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