

# Subjective Evaluation of binaural noise reduction and cue preservation algorithms in a cocktail party scenario

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## INTRODUCTION

- Improve speech intelligibility in binaural hearing aids using binaural beamforming algorithms
- Subjectively compare several binaural algorithms with different design criteria in terms of interference and noise reduction and binaural cue preservation for a cocktail party scenario

### Speech intelligibility:

- 50% SRT measured using Oldenburg Sentence Test (OLSA) with time-compressed speech (compressed to 40%) [1]

### Subjective Preference Test:

- Rank test with spatial scenario (desired + interfering speaker) projected on a screen to provide visual information
- Task: Rate overall preference when listening to the OLSA speaker

## ALGORITHMS / IMPLEMENTATION

### Reference algorithm:

- Bilateral MVDR beamformer (SNR optimal) steered towards 0° (**BIL**)

### Binaural algorithms [2]:

- Binaural **MVDR** (SNR optimal) and binaural **MPDR** (SINR optimal) only preserving binaural cues of target source

### Constrained binaural algorithms [2]:

- Binaural **LCMV** (SNR optimal) and binaural **LCMP** (SINR optimal) also preserving binaural cues of residual interfering source

Algorithms require several quantities to be estimated from the signals:

	Target DOA	Interference DOA	Signal correlation matrix	Diffuse coherence matrix
BIL				Required
MVDR	Required			Required
MPDR	Required		Required	
LCMV	Required	Required		Required
LCMP	Required	Required	Required	

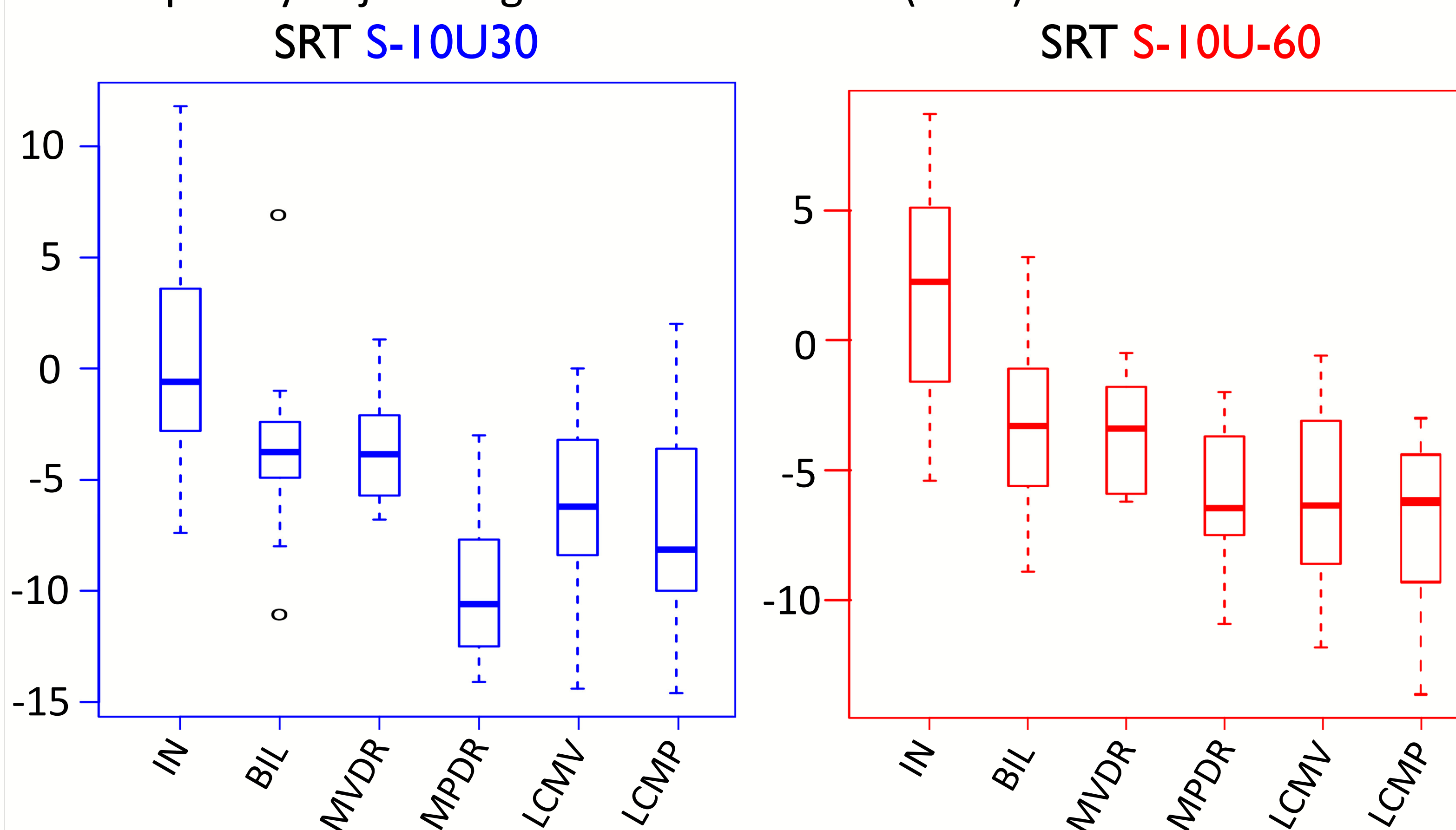
- DOAs estimated using SVM-based method [3], steering vectors and diffuse coherence matrix calculated from anechoic prototype ATFs.
- Weighted-overlap-add,  $f_s=16\text{kHz}$ , 10ms block length, 50% overlap

### Acoustic Scenario:

- Desired source (German speaker) at  $-10^\circ$ , interfering source (English speaker) at  $30^\circ$  (**S-10U30**) or  $-60^\circ$  (**S-10U-60**), diffuse babble noise (SNR: -2dB)

## SPEECH INTELLIGIBILITY RESULTS

- N=14 self-reported normal hearing subjects
- Adaptively adjust target-to-masker-ratio (TMR) to measure SRT50



	IN	BIL	MVDR	MPDR	LCMV	LCMP
IN		*	***	*	***	***
BIL	*			***	***	***
MVDR	*	***		***	*	***
MPDR	***	***	***		**	*
LCMV	***	***	*	**		*
LCMP	***	***	*	*	*	

Significance of SRT differences for **S-10U30** and **S-10U-60**

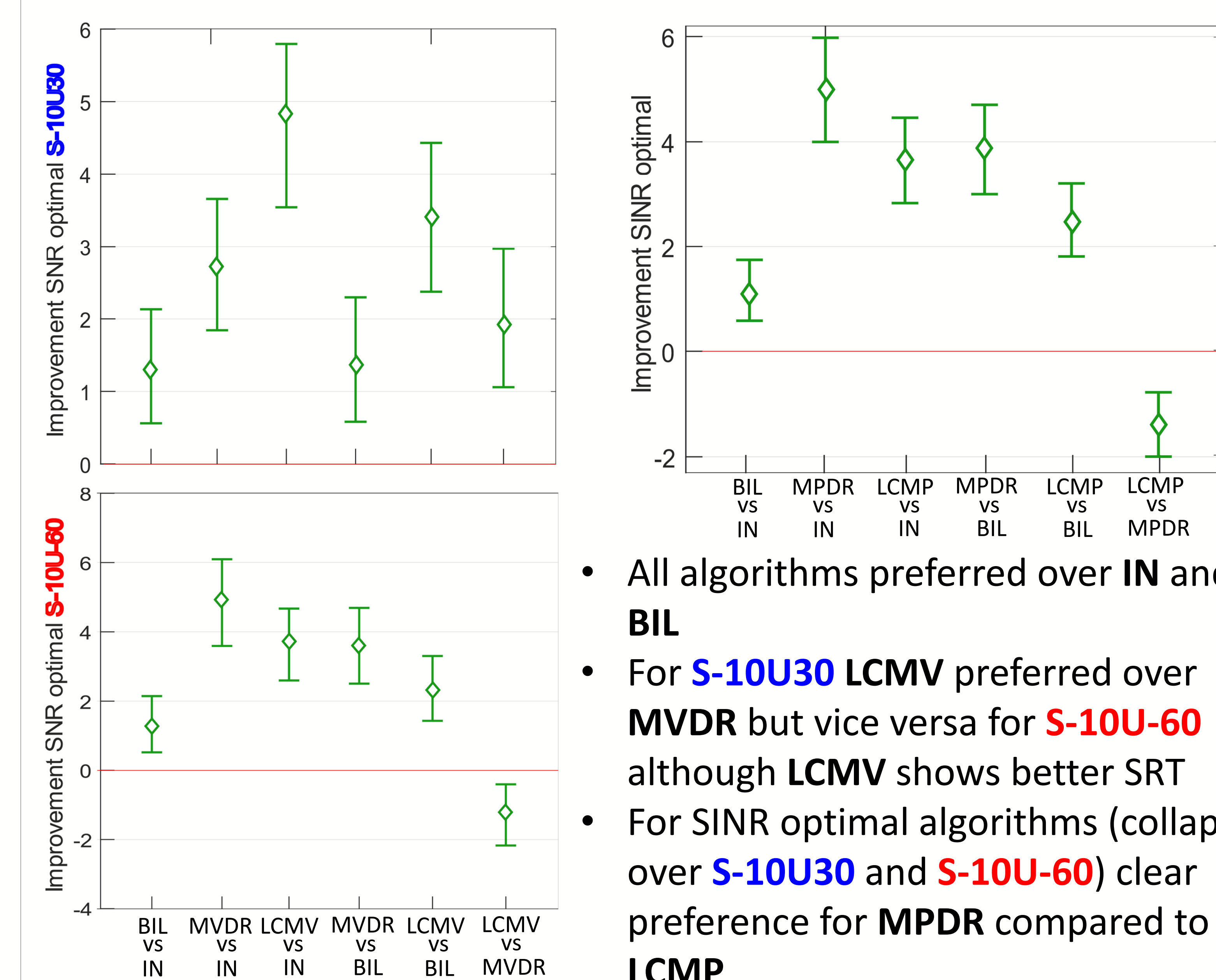
- All considered algorithms significantly improve speech intelligibility
- Binaural **MVDR** does not improve SRT compared to bilateral **BIL** despite better SNR improvement but distortions of interference cues
- **LCMV** outperforms **BIL** and **MVDR** due to additional binaural cue preservation and better suppression of interfering source [2] (only significant for **S-10U-60**)
- **MPDR** clearly outperforms other algorithms for **S-10U30** and **LCMP** shows no improvement over **MPDR**

## REFERENCES

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- [3] H. Kayser and J. Anemüller, "A discriminative learning approach to probabilistic acoustic source localization," in Proc. International Workshop on Acoustic Signal Enhancement (IWAENC), Juan-les-Pins, France, Sep. 2014, pp. 99–103.
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## PREFERENCE TEST RESULTS

- Same **S-10U30** and **S-10U-60** scenarios as for SRT measurements (no time-compressed speech) and TMR of -10 and 0 dB, 4 algorithms compared per experiment in a rank test
- N=9 self-reported normal hearing subjects
- Lack of overlap with zero line indicates significant result [4]



- All algorithms preferred over **IN** and **BIL**
- For **S-10U30** **LCMV** preferred over **MVDR** but vice versa for **S-10U-60** although **LCMV** shows better SRT
- For SINR optimal algorithms (collapsed over **S-10U30** and **S-10U-60**) clear preference for **MPDR** compared to **LCMP**

## SUMMARY

- Binaural algorithms significantly improve speech intelligibility in cocktail party scenarios and are preferred over bilateral algorithms
- SNR optimal algorithms: **LCMV** improves SRT compared to **MVDR** (significant for **S-10U-60**) and is subjectively preferred for **S-10U30**
- SINR optimal algorithms: **LCMP** does not improve intelligibility or preference over **MPDR** for both spatial scenarios

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